

# S-Modular Games and Power Control in Wireless Networks

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# Goals

- show how centralized or distributed power control algorithms in wireless communications can be viewed as S-modular games
- establish convergence results of power control algorithms
- obtain new properties of S-modular games from results that have been obtained for power control problems

# S-modular games

- Refers to Super-modular and Sub-modular
- Super-modular game:
  - if the other players increase their strategy, it pays for you to increase yours
  - strategy space  $S_i$  is a sublattice of  $\mathbf{R}_m$ 
    - i.e.  $S_i$  has a component-wise least element (a.k.a. meet, a.k.a.  $x \wedge y$ ) and a component-wise greatest element (a.k.a. join, a.k.a.  $x \vee y$ )
  - $u_i$  is supermodular in  $s_i$ 
$$u_i(x \wedge y) + u_i(x \vee y) \geq u_i(x) + u_i(y) \quad \text{for any } x \text{ and } y \text{ in } S$$
  - for  $u_i$  twice differentiable, supermodularity is equivalent to
$$\frac{\partial^2 u_i(x)}{\partial x_i \partial x_j} \geq 0$$
- Sub-modular game:
  - if the other players decrease their strategy, it pays for you to decrease yours
  - replace  $\geq$  with  $\leq$

# Important properties of S-Modular Games

- Nash equilibrium exists
- NE can be obtained using a greedy best-response-type algorithm
- best response policies are monotonic in other players' policies

# Constrained Nash Equilibrium

- A joint policy  $x^*$  is a constrained Nash Equilibrium if for each player  $i$

$$x_i^* \in \arg \mathit{opt}_{x_i \in S_i(x_{-i}^*)} u_i(x_i, x_{-i}^*)$$

- $\mathit{opt}$  = max for supermodular, min for submodular
- ie, the strategy for which all players achieve the maximum utility given the (possibly competing) strategies of the other players

# Best Response

- For a supermodular function  $u$

$$BR_i^*(x_{-i}) = \max[\arg \max_{x_i \in S_i(x_{-i})} u(x_i, x_{-i})]$$

- Monotonicity

$$x_{-i} \leq x'_{-i} \Rightarrow BR_i^*(x_{-i}) \leq BR_i^*(x'_{-i}) \Rightarrow S_i(x_{-i}) \prec S_i(x'_{-i})$$

where  $A \prec B$  means for 2 sublattices A and B, the minimum of both sets is in A and the maximum is in B;  
the **ascending property**

# GUA

- General Updating Algorithm
- There are  $N$  infinite increasing sequences  $\{T_k^i\}$ ,  $i=1..N$ ,  $k=1,2,3,\dots$
- Player  $i$  uses at time  $T_k^i$  the best response policy the best response policy to the policies used by all other players just before  $T_k^i$

Note: includes strategic form and extensive form games (playing simultaneously or taking turns)

# Theorem

- Assume that for all  $i=1, \dots, N$ ,  $S_i(\cdot)$  are compact for all values of their argument, and are lower semicontinuous in its argument. Either
  - the game is supermodular, players maximize, and  $S_i(\cdot)$  are ascending
  - the game is submodular, players minimize, and  $S_i(\cdot)$  are descending
- The following hold:

# Theorem, Cont'd

- i An equilibrium exists
- ii If each player  $i$  initially uses its lowest policy in  $S_i$ , or if each player  $i$  initially uses its largest policy in  $S_i$ , then the GUA converges monotonically to an equilibrium.
  - Monotonicity is the same direction for all players: the sequences of strategies either all increase or all decrease
- iii If we start with a feasible policy  $\mathbf{x}$ , then the sequence of best responses monotonically converges to an equilibrium

# Equilibrium Uniqueness

- There exists a unique dominating element in the set of equilibria  $S^*$  (component-wise)
  - ex. submodular game: if  $x_1$  and  $x_2$  are in  $S$ , then  $x' := x_1 \wedge x_2$  is feasible (due to the descending property)
- The unique minimum is attainable using GUA (for any order of updates) starting at the minimal elements of  $S_i$ 
  - at each iteration of best responses, the new actions are no greater than the best responses to  $x_{\min}$ , which is again  $x_{\min}$ , so their limit is bounded by  $x_{\min}$

# Uplink Power Control Problem Statement (Yates)

- N users, M base stations, common radio channel
- transmission power of each user must be greater than some level  $I_j(\mathbf{p})$  that depends on the transmission powers of all users  $\mathbf{p}$
- We wish to obtain  $\mathbf{p}^*$  such that

$$p_i^* = \min \{ p_i \in S_i \text{ s.t. } p_i \geq I_i(\mathbf{p}^*) \}$$

where  $S_i$  is the set of positive real numbers  
(unbounded, but can also restrict)

# Properties of $I(\mathbf{p})$

- Positivity:  $I(\mathbf{p}) > 0$
- Monotonicity: if  $\mathbf{p}' \geq \mathbf{p}$  then  $I(\mathbf{p}) \geq I(\mathbf{p}')$
- Scalability: For  $a > 1$ ,  $aI(\mathbf{p}) \geq I(a\mathbf{p})$

# Problem Statement using Game Theory

- “Strategic normal form”
- $N$  players  $i=1, \dots, N$
- Pure strategy space  $S_i = \mathbf{R}_m$
- Utility of each player is a function of transmission power
- Minimization performed for each mobile

# The Heart of the Paper

- Assume that there is a feasible solution  $\mathbf{p}'$  to  $\mathbf{p} \geq \mathbf{l}(\mathbf{p})$ .
- Then
  - i) there exists a fixed point to the equation  $\mathbf{p} = \mathbf{l}(\mathbf{p})$ ;
  - ii) if the sets  $S_i$  are discrete, then GUA converges for initial powers of all users corresponding to the lowest or to the largest powers;
  - iii) if the sets  $S_i$  are convex (continuous action spaces) then there is a unique fixed point to the equation  $\mathbf{p} = \mathbf{l}(\mathbf{p})$ . Moreover, GUA converges for any initial policy.

# Proof

- Feasibility of  $\mathbf{p}'$  implies  $a\mathbf{p}'$  is feasible for all  $a \geq 1$  (scalability of  $I$ )
- Consider  $\mathbf{p}_0$ , not necessarily feasible
- Consider the following submodular game:
  - actions of player  $j$  is power  $x_j = p_j$
  - utility of player  $j$  is  $u(p_j) = p_j$
  - constraint policy set of player  $j$  is
    - $S_j(p_{-j}) = \{ p_j : p_j \geq I_j(p), 0 \leq p_j \leq ap'_j \}$
    - a subset of the compact set  $S_j = \{ p_j : 0 \leq p_j \leq ap'_j \}$

# Proof, cont'd

- Cost of every player  $j$  is trivially submodular (depends only on  $j$ , so derivative = 0)
- policy set of each user is a compact sublattice
- monotonicity of  $I$  implies the decending property
- $S_j$  nonempty for all  $j$

# Proof, cont'd

- in case of continuous strategy spaces, need to check that  $S_j$  are lower semicontinuous
  - $S_j(\cdot)$  are nonempty convex sets
  - Let  $\mathbf{p} = \mathbf{p}^1 \vee \mathbf{p}^2$ .
  - Choose the smallest  $a \geq 1$  such that  $\mathbf{p}/a \leq a\mathbf{p}^j$
  - Monotonicity and scalability of  $I$  imply
    - $aI(\mathbf{p}/a) \geq I(\mathbf{p}) \geq I(\mathbf{p}/a)$
  - Monotonicity and scalability of  $I$  imply
    - $I(\mathbf{p})/a \leq I(\mathbf{p}/a) \leq I(\mathbf{p}^j) \leq I(\mathbf{p})$
    - $|I(\mathbf{p}^1) - I(\mathbf{p}^2)| \leq I(\mathbf{p})(1-1/a)$
  - If  $\mathbf{p}^2$  tends to  $\mathbf{p}^1$  then  $a$  tends to 1 which shows the continuity of  $I$

# Power Constraints

- solution might converge to a point that is not feasible for some mobiles
- instead minimize  $f(p_j, I_j(p))$ , where  $f$  is some increasing function on the absolute value of the difference between the arguments